Q.P. Code: 27639

		[Time: 3 Hours]	[Marks: 80]
	N.B:	Please check whether you have got the right question paper.  1. Question No.l is compulsory  2. Attempt any three questions out of remaining five questions  3. Figures to right indicate full marks  4. Assume suitable data if necessary	
		5. Notations carry usual meaning	
Q.1 (A)	<ol> <li>Piezoele</li> <li>Universa</li> </ol>	sal Asynchronous Receiver and Transmitter (UART) oil actuator ggers	05
Q.2 (A)	With neat slin hydraulic	sketch explain the constructional feature and working of pressure re	lief valve used 05
	Describe po	ossible speed control strategies of A.C. Induction motors ort note on servo amplifier for DC motors	05 10
Q.3 (A)	sequence of (AB)+ Dela Develop the valves. The Explain imp	e acting pneumatic cylinders A, B are selected for an industrial appli of movement for piston of the cylinder is proposed as below— ay B+ A- e electro-pneumatic circuit using 5/2 double solenoid as final direct e piston motions mentioned in bracket is simultaneous. pedance matching for a part of electro-mechancial system that consistent of power using motor-gear drive system.	tional control
	Managemer		
	pneumatic	diagrams illustrate the working of Filter-Regulator- Lubricator (FRL system) te between Serial communication and parallel communication inter	
Q.5 (A)	of the bottle i)The start	r motor is required to program using a PLC in a process line based on ing off the conveyor as shown in Figure I.A photo-sensor is used to sele. Develop a PLC ladder logic diagram for the following sequential to pushbutton can be pressed to start the conveyor motor stops automove past the photo-sensor and the conveyor motor stops automove bottles.	ense the passage asks

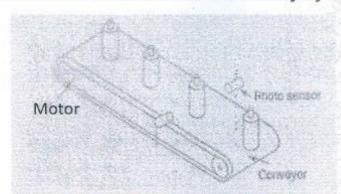
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05 05

10

iii) The counter is to be reset to zero after 25 counts

The accumulated count of the counter is reset manually by means of the count reset button



- (B) Explain the central theme of velocity profile optimization of DC motor
- (C) Explain with neat sketch principle of operation of AC induction motor
- Q.6 (A) With schematic representation explain the mechatronic system typically used in robot for 10 firefighting application (typically highlight the selection of motor, sensors and switches. Also discuss their interfacing.
  - (B) Write short note on (i) Supervisory control and data acquisition (ii) Harmonic drive

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Page 2 of 2