Paper / Subject Code: 32003 / Control System - I

Tuesday, May 21, 2019 02:30 pm - 05:30 pm 1T00825 - T.E.(ELECTRICAL)(Sem V) (Choice Based) / 32003 - Control System-1 58387

Time: (3 Hours)

Total Marks – 80

N.B.:- (1) Question No.1 is compulsory.

- (2) Attempt any three questions out of remaining five questions.
- (3) Draw neat diagrams wherever it is necessary.
- Q 1. Answer any four of the following questions.

20

A) Compare Open loop and Closed loop control system.

205

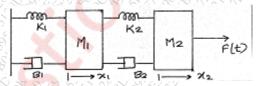
B) Explain the following rules with suitable examples;

5

- (i) Blocks in series
- (ii) Blocks in parallel
- C) Explain Routh-Hurwitz criteria of stability with suitable example.
- 5
- D) What are the advantages of using state space analysis over classical control 5 approaches?
 - E) What is Nyquist stability criteria?

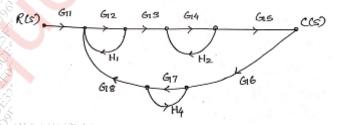
5

Q 2 a) Obtain the differential equations and transfer function describing the mechanical system 10 shown in fig. and also draw its electric network.



Q 2 b) Find the transfer function C(s)/R(s) for the signal-flow graph in figure.

10



Paper / Subject Code: 32003 / Control System - I

Q 3 a) Write a short note on: Time response specifications.

- 10
- Q 3 b) The unity feedback system is characterized by an open loop transfer function G(s) = 10 $\frac{K}{S(S+10)}$ Determine gain K, so that the system will have a damping ratio of 0.5. for this value of K, determine, T_s , T_p an M_p for a unit step.
- Q 4 a) Define (i) State (ii) State variables (iii) State vector (iv) State space. How to obtain the 10 state variable form from transfer function?
- Q 4 b) Obtain the state representation in phase variable form of the following transfer function. 10 $\frac{C(s)}{R(s)} = \frac{12S^2 + 42S + 158}{S^3 + 10S^2 + 56S + 158}$ Also draw state space model.
- Q 5 a) Sketch the root locus of a unity feedback system having $G(s)H(s) = \frac{K}{S(S+4)(S+10)}$ given, also determine the value of K for $\xi = 0.5$.
- Q 5 b) Explain Angle and Magnitude condition. Also explain the steps to find intersection 10 points of root locus with imaginary axis.
- Q 6 a) For the unity feedback control system $G(s) = \frac{10}{S(S+1)(S+5)}$ Sketch the bode plot. Also determine GM, PM, gain and phase crossover frequencies.
- Q 6 b) Discuss the stability of system using Nyquist plot for $G(s)H(s) = \frac{20}{S(S+4)(S-2)}$ 10
