1T01124 - S.E.(ELECTRONICS)(Sem IV)(Choice Based) / 40906 - LINEAR CONTROL SYSTEMS

Time: 3 Hours

- **N.B.** (1) Question number 1 is compulsory.
 - (2) Attempt any 3 questions from remaining.
 - (3) Assume suitable data if required.
 - (4) Figure to the right indicates full marks.

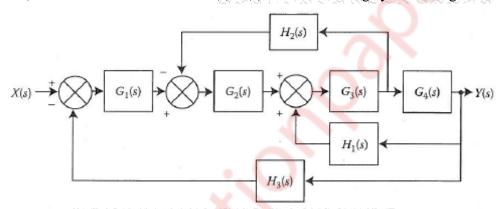
Q1. Attempt any four questions.

[20]

[10]

Marks: 80

- a) Explain needs of compensation in control system also explain different types of Compensation with suitable example.
- b) What are the properties of state transition matrix?
- c) Define Gain margin and Phase margin. Explain how these margins are used for stability analysis
- d) Give comparison between open loop and closed loop control systems.
- e) Explain the effect of addition of pole and zero to a system.
- Q2. A) Find the transfer function C(s)/R(s) of the following system using block diagram technique. [10]



Q2. B) Determine breakaway points and break-in points for the characteristics equation given as [10]

$$1 + \frac{K(s+2)(s+3)}{s(s+1)} = 0$$

Plot the Root Locus for the system.

Q3. A) Derive an expression for peak time and settling time of an under damped second order system. [10]

Q3. B) Obtain the state variable model of the transfer function –

 $\frac{Y(s)}{R(s)} = \frac{5s+4}{s^2+4s+3}$

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- Q4. A) Apply Kalmans test for checking the controllability of given state equation.
- [10]

$$\dot{X} = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -6 & -11 & -6 \end{bmatrix} \begin{bmatrix} \chi_1 \\ \chi_2 \\ \chi_3 \end{bmatrix} + \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} u(t)$$

- Q4. B) Ascertain stability of the system whose characteristic equation is 6 + 3s5 + 5s4 + 9s3 + 8s2 + 6s + 4 = 0. Also find the number of roots lying on the left half, right half and imaginary axis of the s-plane.
- Q5. A) Construct the Bode Plot for the following transfer function. Determine the following: [10]
 - i) Gain Margin
- ii) Phase margin
- iii) Closed loop stabiity

[10]

$$G(s)H(s) = \frac{4}{s(s+0.5s)(1+0.08s)}$$

- Q5. B) List the performance specifications of Time Response Analysis and derive any four of them. [10]
- Q6. A) State Adaptive Control System significance in engineering applications
- [05]

Q6. B) Explain PID Controller.

[05]

Q6. C) Explain the effect of adding a pole to a system on time response.

Q6. D) Draw polar plot for the transfer function given by

[05]

[05]

 $G(s) = \frac{8}{s(1+s)}$

